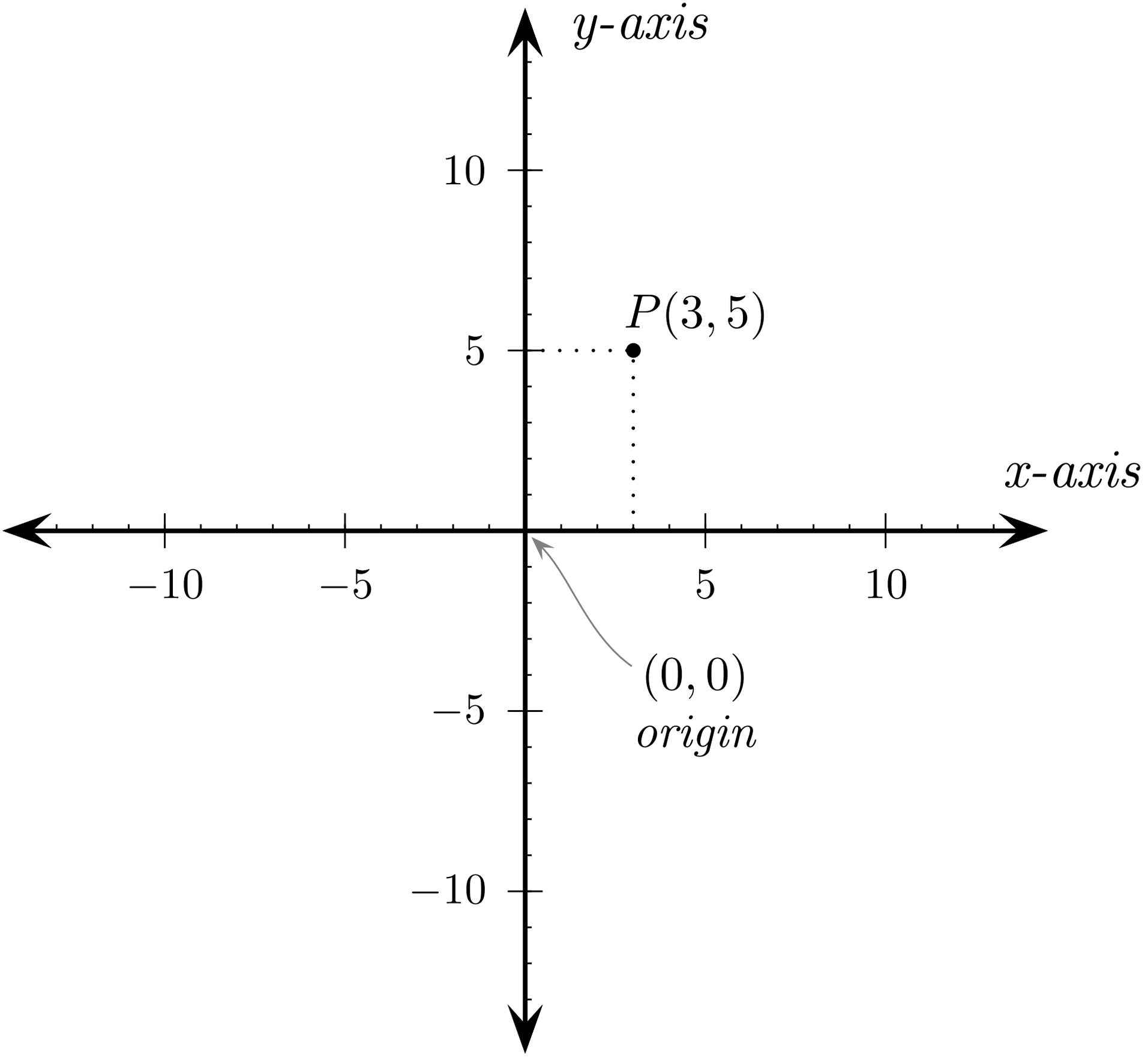
y-axis
10
P(3, 5)
5
x-axis
−10
−5
5
10
(0, 0)
origin
−5
−10